# CME 213, ME 339—Spring 2021

# Eric Darve, ICME, Stanford



"Where is the 'any' key?" — Homer Simpson, in response to the message, "Press any key"

# Distributed memory computing using MPI



Shared memory is a good model for a small number of processes.

When dealing with a large number of processors, we need to view the memory as being distributed.

What this means:

Processors can no longer directly read and write to another processor's memory



Instead processors exchange messages.

Programmed by the user explicitly.

Send + Receive



This can be done using MPI.

MPI is the standard for distributed memory computing.

Message Passing Interface

# Flynn's taxonomy

SIMT: one instruction is dispatched to multiple threads.

Warp on a GPU



SIMD: same instruction run by different processing units using different data

Vector processing units



## MIMD: multiple instructions, multiple data; multiple threads running different functions

Multicore threads



SPMD: this is our topic for today.

The same program runs on different processors.

Processors communicate through a network by exchanging messages or data in an explicit manner.

Each program has a unique ID or rank which is used to determine what computations the program should perform.





## Where can I get MPI?

- OpenMPI: [www.open-mpi.org](https://www.open-mpi.org/) (what we use on icme-gpu)
- MVAPICH: [mvapich.cse.ohio-state.edu](http://mvapich.cse.ohio-state.edu/)
- MPICH: [www.mpich.org](https://www.mpich.org/)

## What computer can I use it with?

You can test MPI using a multicore computer.

Each process runs on its own core.

You can run this on your laptop or icme-gpu.

# Compiling

Compile with: mpic++

Header: mpi.h

Running is more complicated than usual.

You need to start multiple programs (processes) on multiple computers.

You need to make sure all processes are killed or terminated at the end.

⇒ sbatch, mpirun

sbatch: batch submission

Your job will be placed in a queue and run when resources are available.

The output is written to a file.

```
#!/bin/bash
```

```
#SBATCH --time=00:30:00
#SBATCH --partition=CME
#SBATCH --nodes=1
#SBATCH --ntasks-per-node=4
#SBATCH --gres=gpu:4
#SBATCH --job-name=fp
#SBATCH --output=fp-%j.out
#SBATCH --error=fp-%j.err
mpirun ./mpi_hello
```


### Or:

### #!/bin/bash

```
#SBATCH --time=00:30:00
#SBATCH --partition=CME
#SBATCH --nodes=1
#SBATCH --gres=gpu:4
#SBATCH --job-name=fp
#SBATCH --output=fp-%j.out
#SBATCH --error=fp-%j.err
```
mpirun -n 4 ./mpi\_hello



With mpirun, we are running the program mpi\_hello four times.

## Example:

#!/bin/bash

```
#SBATCH --partition=CME
#SBATCH --nodes=1
#SBATCH --ntasks-per-node=4
```
mpirun hostname



## Output:

icmet01 icmet01 icmet01 icmet01

mpi\_hello.cpp

### MPI\_Init(&argc, &argv);

```
// How many processes are running
int numprocs;
MPI_Comm_size(MPI_COMM_WORLD, &numprocs);
// What's my rank?
int rank;
MPI_Comm_rank(MPI_COMM_WORLD, &rank);
// Which node am I running on?
int len;
char hostname[MPI_MAX_PROCESSOR_NAME];
MPI_Get_processor_name(hostname, &len);
printf("Hello from rank %2d running on node: %s\n"
, rank, hostname);
if (rank == MASTER)
```
printf("MASTER process: the number of MPI processes is: %2d\n" , numprocs);

MPI\_Finalize();



# Computing  $\pi$  using MPI

```
\frac{1}{2} salloc -N 1 -n 4 --partition=CME mpirun mpi_pi_send
MPI process 0 has started on icmet01 [total number of processors 4]
MPI process 3 has started on icmet01 [total number of processors 4]
MPI process 1 has started on icmet01 [total number of processors 4]
MPI process 2 has started on icmet01 [total number of processors 4]
   After 2000000 throws, average value of pi = 3.14071400After 4000000 throws, average value of pi = 3.14121500After 6000000 throws, average value of pi = 3.14127600After 8000000 throws, average value of pi = 3.14107900After 10000000 throws, average value of pi = 3.14110760
   After 12000000 throws, average value of pi = 3.14155867After 14000000 throws, average value of pi = 3.14151857After 16000000 throws, average value of pi = 3.14160475After 18000000 throws, average value of pi = 3.14165844After 20000000 throws, average value of pi = 3.14163500
```
Exact value of pi: 3.1415926535897



mpi\_pi\_send.cpp

```
if (rank != MASTER)
{
    int tag = i;
    int rc = MPI_Send(&my_pi, 1, MPI_DOUBLE,
                         MASTER, tag, MPI_COMM_WORLD);
    if (rc != MPI_SUCCESS)
          printf("%d: Send failure on round %d\n"
, rank, tag);
}
else
{
     \bullet\quad\bullet\quad\bullet}
```


```
int MPI_Send(void *smessage, int count,
    MPI_Datatype datatype, int dest,
    int tag,
    MPI_Comm comm)
```
smessage buffer which contains the data count number of elements to be sent datatype data type of entries dest rank of the target process tag message tag which (used to distinguish messages) comm communicator used for the communication



```
if (rank != MASTER) { ... } else {
    int tag = i; double pisum = 0;
    for (int n = 1; n < numprocs; n+1) {
        double pirecv; MPI_Status status;
        int rc = MPI_Recv(&pirecv, 1, MPI_DOUBLE, MPI_ANY_SOURCE,
                            tag, MPI_COMM_WORLD, &status);
        if (rc != MPI_SUCCESS)
            printf("%d: Receive failure on round %d\n"
, rank, tag);
        /* Running total of pi */
        pisum += pirecv;
    }
```
}



```
int MPI_Recv(void *rmessage, int count,
    MPI_Datatype datatype, int source,
    int tag, MPI_Comm comm,
    MPI_Status *status)
```
Mostly same as before. One new argument:

status data structure that contains information about the message that was received

```
if (rank != MASTER) {
    int tag = i;
    int rc = MPI_Send(&my_pi, 1, MPI_DOUBLE,
                    MASTER, tag, MPI_COMM_WORLD);
} else {
    for (int n = 1; n < numprocs; n+1) {
        int rc = MPI_Recv(&pirecv, 1, MPI_DOUBLE, MPI_ANY_SOURCE,
                        tag, MPI_COMM_WORLD, &status);
        pisum += pirecv;
    }
}
```


## Rules and order

Each Send must be matched with a corresponding Recv.

Order: messages are received in the order in which they have been sent.

If a sender sends two messages of the same type one after another to the same receiver, the MPI runtime system ensures that the first message sent is always received first.



# Collective communications

What we have discussed so far is **point-to-point communication,** that is one process communicates with another process.



Let's say that we have a group of processes that need to exchange data.

For example we want to do a reduction.

This is called a collective communication, i.e., multiple processes need to communicate.

For best performance, we need to orchestrate the communication.

Simply having each process send its data to the master node is inefficient.







## Computer network = network of highways

Each highway has a number of lanes and a maximum traffic it can support. This is the bandwidth.



Depending on the network topology, there is an optimal algorithm to route the messages in order to minimize the total wall clock time of the collective communication.

Three key issues:

- 1. These communication algorithms can be complicated.
- 2. They depend on the network topology.
- 3. There are relatively few collective communication patterns that get reused over and over again.

# Let's review the main functions

MPI\_Bcast(&buffer,count,datatype,root,comm)



MPI\_Reduce(&sendbuf,&recvbuf,count,datatype,op,root,comm)







Using 16 tasks to scan 40000000 numbers... Done. Largest prime is 39999983. Total number of primes found: 2433654 Wall clock time elapsed: 3.19 seconds

mpi\_prime.cpp



```
for (int n = mystart; n \le LIMIT; n \ne N stride) {
    if (IsPrime(n)) {
        pc++; // found a prime
        foundone = n; // last prime that we have found
    }
}
// Total number of primes found by all processes: MPI_SUM
MPI_Reduce(&pc, &pcsum, 1, MPI_INT, MPI_SUM, MASTER, MPI_COMM_WORLD);
// The largest prime that was found by all processes: MPI_MAX
```
MPI\_Reduce(&foundone, &maxprime, 1, MPI\_INT, MPI\_MAX, MASTER, MPI\_COMM\_WORLD);







### MPI\_Scatter(&sendbuf,sendcnt,sendtype,&recvbuf,recvcnt,recvtype,root,comm)



# Final project

Rank 0 reads MNIST data from disk

MPI\_Scatter the images to all processors

MPI\_Allgather(&sendbuf,sendcount,sendtype,&recvbuf,recvcount,recvtype,comm)



### MPI\_Allreduce(&sendbuf,&recvbuf,count,datatype,op,comm)



## Final project

$$
J(p) = \frac{1}{N} \sum_{i=1}^N \text{error}^{(i)}(y_i, \hat{y}_i) \\ \\ p \leftarrow p - \alpha \nabla J_p
$$

Each process has a partial  $\nabla J_p$ 

MPI\_Allreduce to get the complete gradient on all processors



Rank 0 has the lowest value of 839





## proc\_min\_value.cpp

```
int localres[2], globalres[2];
localres[0] = localarr[0]; // Minimumfor (int i = 1; i < locn; i+1)
   if (localarr[i] < localres[0])
        localres[0] = localarr[i];
```
// The second entry is the rank of this process.  $localres[1] = rank;$ 

// MPI\_MINLOC: like the operator min. The difference is that it // takes as input two numbers; the first one is used to determine the // minimum value. The second number just goes along for the ride. // MPI\_2INT: type for <sup>2</sup> integers. MPI\_Allreduce(localres, globalres, 1, MPI\_2INT, MPI\_MINLOC, MPI\_COMM\_WORLD);





